

# Overview:

P.1

What models have we done so far?

- Falling objects  $h'' = g$
- Population growth / Compound interest

$$N(t+\Delta t) = (1+r\Delta t)N(t)$$

$$\Rightarrow \frac{dN}{dt} = rN$$

- Growth + constant harvesting / mortgage payments.

$$P(t+\Delta t) = (1+r\Delta t)P(t) - M(\Delta t)$$

$$\Rightarrow \frac{dP}{dt} = rP(t) - M \quad (\text{for example})$$

These are, in many ways, the simplest models we can come up with. They're 1st order, they all have analytical solutions, they involve only constant and/or linear terms, they're deterministic.

These models (especially (2)) will form the basis for everything else we do - everything else is just adding in complications/realism.

This week, we'll add our first wrinkle: nonlinearity.

Since ODEs are generally easier to work with than difference equations, we'll start with continuous models.

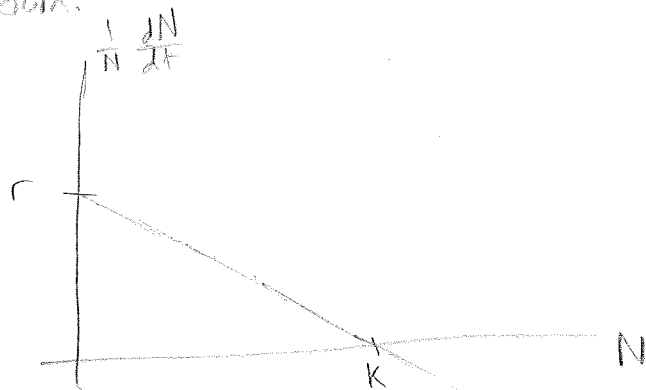
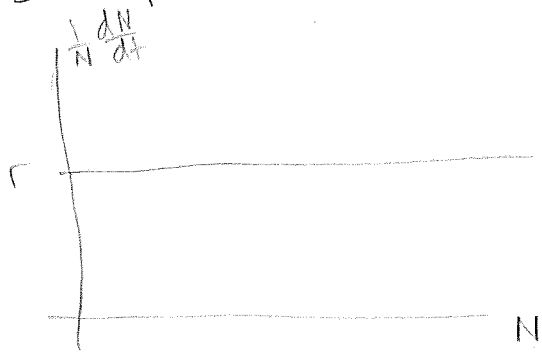
# Back to Population growth:

$\frac{dN}{dt} = rN$ , where  $N$  is the population and  $r$  is the growth rate per organism

In particular, notice that

$$r = \frac{1}{N} \frac{dN}{dt} = \text{the per capita growth rate.}$$

That is, the per capita growth rate is constant w/ respect to both time and population. This doesn't really make sense: if it's more crowded, mortality should go up, so  $r$  should go down.



The simplest way to add this density dependence is to make  $\frac{1}{N} \frac{dN}{dt} = R(N)$  decay linearly, w/  $R(0) = r$  and  $R = 0$  at some large population  $K$ . I.e.,

$$R(N) = r \cdot \left(1 - \frac{N}{K}\right), \text{ so}$$

$$\frac{1}{N} \frac{dN}{dt} = r \cdot \left(1 - \frac{N}{K}\right) \Rightarrow \frac{dN}{dt} = r \cdot N \cdot \left(1 - \frac{N}{K}\right).$$

This is called the logistic equation (or occasionally the Pearl-Verhulst equation)

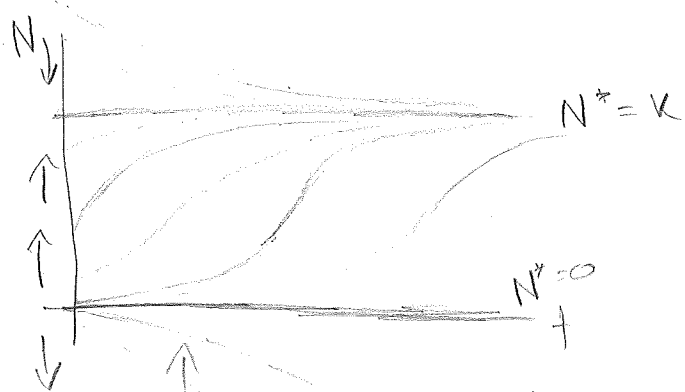
# Logistic Growth:

We can actually solve this equation explicitly, but we won't always be so lucky. With that in mind, let's see what we can understand without finding  $N(t)$ .

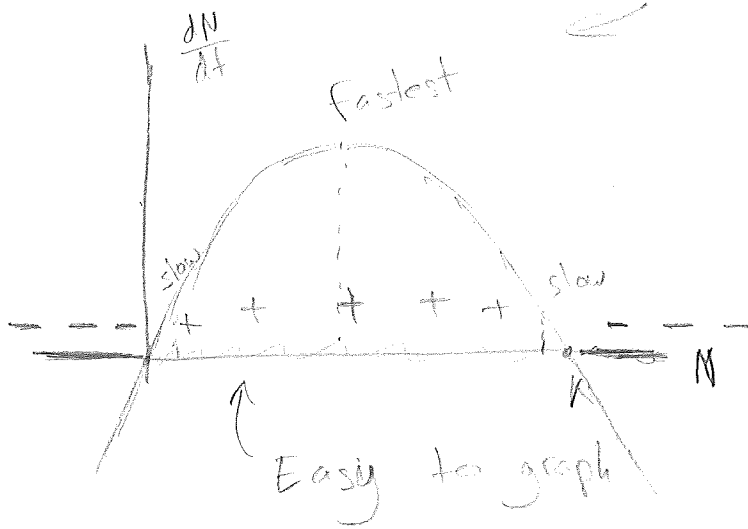
First, we want to find out when the population doesn't change. That is, we're looking for values of  $N$  where  $\frac{dN}{dt} = 0$ .

$$\frac{dN}{dt} = r \cdot N \cdot \left(1 - \frac{N}{K}\right) = 0 \Rightarrow N=0 \text{ or } 1 - \frac{N}{K} = 0 \Rightarrow N=K$$

Two equilibria:  $N^* = 0$  and  $N^* = K$  Assume  $r > 0$



What we want to graph



$N^* = 0$  is called unstable - solutions move away from it.

$N^* = K$  is called stable - solutions move towards it.

# Logistic Growth continued:

P.4

Stability looks obvious from the graph, but we shouldn't trust graphs too much. Can we prove it?

Before we do any analysis we should make a change of variables. Stability involves the idea that  $N$  is "close to"  $N^*$ , which means  $N - N^*$  is small, but we said variables with units shouldn't be called small or large. Instead, we should compare them to some other variable w/ the same units. To this end, let  $x = \frac{N}{K}$ . (unitless)

$$\Rightarrow N = Kx, \text{ so } \frac{dN}{dt} = K \frac{dx}{dt} \Rightarrow$$

$$\frac{dN}{dt} = r \cdot N \cdot \left(1 - \frac{N}{K}\right)$$

$$\downarrow$$
$$K \frac{dx}{dt} = r \cdot Kx \cdot (1 - x)$$

$$\Rightarrow \dot{x} = rx \cdot (1 - x)$$

This means  $x^* = 0$  and  $x^* = 1$

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Stability of  $x^* = 0$ :

Suppose  $x$  is close to  $x^* = 0$  - i.e.,  $|x| \ll 1$ .

$$\frac{dx}{dt} = rx - rx^2$$

If  $x$  is small, then  $x^2$  is much smaller, so

$$\frac{dx}{dt} \approx rx$$

$\Rightarrow$  This is just exponential growth. Since  $r > 0$ , solutions move away from 0, so  $x^* = 0$  is unstable

# Stability of $x^* = 1$ .

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Suppose  $x$  is close to 1. That is,  $x - 1$  is small.

To make life easier, let  $y = x - 1$ , so  $y \ll 1$ .

$$\frac{dy}{dt} = \frac{dx}{dt}$$

$$\text{We have } \frac{dy}{dt} = r \cdot (y+1) \cdot (1 - (y+1)) = r \cdot (y+1) \cdot (-y) = -ry^2 - ry.$$

since  $y$  is small,  $y^2$  is much smaller, so

$$\frac{dy}{dt} \approx -ry.$$

This is exponential decay. Since  $r > 0$ , solutions <sup>(to  $y$ )</sup> move towards 0, so  $y \rightarrow 0$ , so  $x \rightarrow 1$ , so  $x^* = 1$  is stable.

Notice:  $\dot{x} = r \cdot x \cdot (1-x) = f(x)$

$$f'(x) = r - 2rx, \text{ so } f'(0) = r \text{ and } f'(1) = -r.$$

These are the same as the coefficients we found in our stability analysis. Is that a coincidence?



If slope of tangent line is positive, then  $\frac{dx}{dt} > 0$  for  $x > x^*$  and  $\frac{dx}{dt} < 0$  for  $x < x^*$ . If slope is negative,  $\frac{dx}{dt} < 0$  for  $x > x^*$

and  $\frac{dx}{dt} > 0$  for  $x < x^*$ .

In general,  $x^*$  is stable if  $f'(x^*) < 0$  and unstable if  $f'(x^*) > 0$ .

A slightly more interesting example (but a bad population model):

$$\frac{dx}{dt} = rx(1-x) - h, \text{ where } h \text{ is a constant (and } r > 0).$$

What are the equilibria, and are they stable?

$$rx(1-x) - h = 0$$

$$\Rightarrow rx - rx^2 - h = 0$$

$$\Rightarrow rx^2 - rx + h = 0$$

$$\Rightarrow x = \frac{r \pm \sqrt{r^2 - 4rh}}{2r}$$

# of fixed points depends on  $r$  and  $h$ .

$$\text{If } r^2 - 4rh > 0 \Rightarrow r - 4h > 0 \Rightarrow h < \frac{r}{4}$$

then there are two fixed points.

$$x_1^* = \frac{r + \sqrt{r^2 - 4h}}{2r}, \quad x_2^* = \frac{r - \sqrt{r^2 - 4h}}{2r}$$

Are they stable?

$$f'(x) = r - 2rx, \text{ so}$$

$$\begin{aligned} f'(x_1^*) &= r - 2r \cdot \left( \frac{r + \sqrt{r^2 - 4h}}{2r} \right) \\ &= r - r - \sqrt{r^2 - 4h} \\ &= -\sqrt{r^2 - 4h} < 0, \end{aligned}$$

so  $x_1^*$  is stable

$$\begin{aligned} f'(x_2^*) &= r - 2r \cdot \left( \frac{r - \sqrt{r^2 - 4h}}{2r} \right) \\ &= r - r + \sqrt{r^2 - 4h} \\ &= \sqrt{r^2 - 4h} > 0, \end{aligned}$$

so  $x_2^*$  is unstable.

If  $r^2 - 4h = 0$ , so  $h = \frac{r^2}{4}$ , there is only one equilibrium.

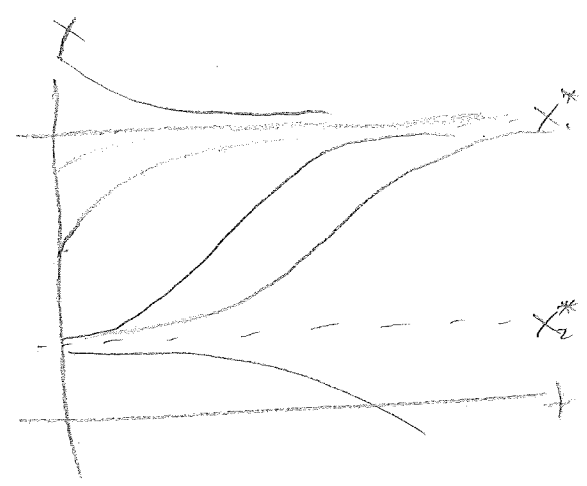
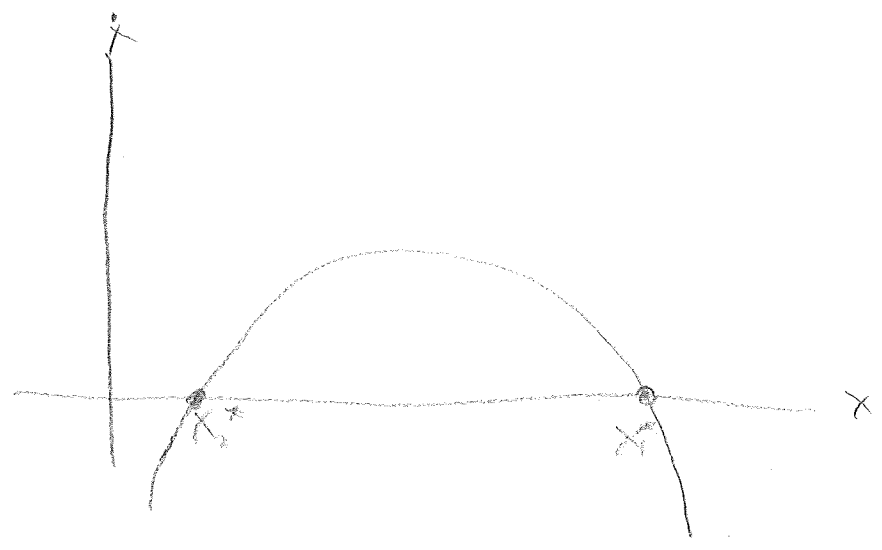
$$x^* = \frac{r}{2r} = \frac{1}{2}.$$

$$f'(x^*) = r - 2r \cdot \left( \frac{1}{2} \right) = r - r = 0 \quad ?$$

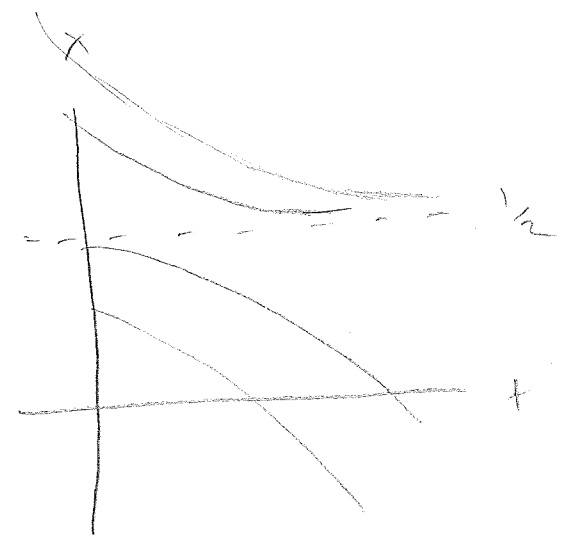
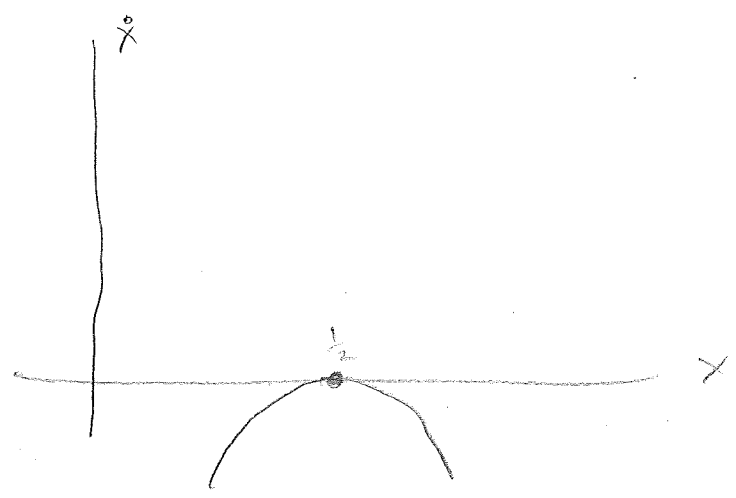
If  $r^2 - 4h < 0$ , there are no equilibria.

Phase line:

$$h > \frac{r}{4}$$



$$h = \frac{r}{4}$$



$$h < \frac{r}{4}$$

